# LINEAR TRANSDUCERS

# HIGH RELIABILITY EVEN IN THE HEAVY ENVIRONMENTS.

Easy installation made easier for the presence of a groove in the housing potentiometer represent an ideal solution for the most used machine of material manufacture, for example injection press for plastic and gum. ELTRA's linear transducers are engineered for high accuracy, high cycle-life and easy installation. Standard strokes are from 10 (4/10") mm to 1250 mm (4 ft). ELTRA's linear transducers provide accurate sensing in a wide range of configurations. Rod style for fitting within hydraulic pistons or profile housing for a convenient mounting are available.

ELTRA's linear sensors feature absolute positioning, greater reliability, easy control, noise reduction, robustness, increased productivity, reduced shock and stress on mechanical parts, high precision for high performances, cost-effective solutions.



# ERA/B/C/D/E/F INCREMENTAL LINEAR ENCODER



Incremental linear system based on optical or magnetic principle. Easy mounting due to to joint heads.

- 0,01 mm max resolution (after quad eval)
- Available with or without zero mark on left, right or central position
- · Up to 1 m/s travel speed
- Working stroke up to 500 mm
- · Cable output, connector available on cable end
- · Mounting by joint heads



ORDERING CODE	ER	A	100	S	8/24	N	6	Р	. XXX
	SERIES								
	incremental linear encoder ER								
	RES	0.2  mm							
	(	0,1 mm B							
	0,	04 mm C							
		0,5 mm E							
		0,2 mm F							
	working strake (m	WORKING	G STROKE						
	working stroke (iii	111) 110111 1	00 10 500 7FF						
		v	without zer	o pulse S					
	(mad A) right	(mod. A)	central zer	o index C					
	(moa. A) right (mod. A) le	zero index ft zero ind	ex (open p	osition) D					
			5-FF	POWEI	R SUPPLY				
				0 241	5 V DC 5				
				0 24 V	TRONIC IN	TERFACE			
				LLLU	(mod.	A) NPN N			
				(mod. A) N	PN open c	ollector C			
					pu lin	sn-pull P e driver L			
					FIXI	NG HOLE D	IAMETER		
							mm <mark>6</mark>		
					radial aa	bla (stand	OUTF ord longth		
					raulai Ca	nie (219110)	aru ieligtii	1,3 III) P I	VARIANT
							C	custom ver	sion XXX





#### LINEAR TRANSDUCERS | ER A / B / C / D / E / F

# ER A / B / C / D / E / F





dimensions in mm

# ELECTRICAL SPECIFICATIONS

Technology	optical mod. A magnetic mod. B / C / D / E / F
Resolution	1 mm (0,25 mm after quad eval) 0,5 mm (0,125 mm after quad eval) 0,2 mm (0,05 mm after quad eval) 0,1 mm (0,025 mm after quad eval) 0,04 mm (0,01 mm after quad eval)
Linearity error	$\pm$ 0,05 mm max (mod. A / F) $\pm$ 0,025 mm max (mod. B) $\pm$ 0,01 mm max (mod. C) $\pm$ 0,125 mm max (mod. E) $\pm$ 0,25 mm max (mod. D)
Power supply	5 = 4,5 5,5 V DC 8/24 = 7,6 25,2 V DC
Current consumption without load	< 100 mA max
Max load current	50 mA / channel (NPN / NPN open) 20 mA / channel (push pull / line driver)
Output type*	NPN / NPN open collector / push-pull / line driver
Max output frequency	100 kHz
Counting direction	A leads B (piston open) mod.A B leads A (piston open) mod. B / C / D / E / F
Electromagnetic compatibility	IEC 61000-6-2 IEC 61000-6-4

\*output levels according to power supply, for further details please see under Technical basics section

#### MECHANICAL SPECIFICATIONS

Working stroke	100 - 150 - 200 - 250 - 300 - 350 - 400 - 500 mm				
Enclosure rating	IP 64 (IEC 60529)				
Travel speed	1 m/s max				
Shock	50 G, 11 ms (IEC 60068-2-27)				
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)				
Rod material	1.4305 / AISI 303 stainless steel				
Housing material	painted aluminum				
Fixing	2 joint heads with ø 6 mm hole				
Operating temperature	-10° +60°C (+14° +140°F)				
Storage temperature	-25° +70°C (-13° +158°F)				
Weight	400 1000 g (14,11 35,27 oz)				

CONNECTIONS		
Function	Cable output N / C / P	Cable output Line driver
+V DC	red	red
0 V	black	black
Ch. A	green	green
Ch. A-	/	brown
Ch. B	yellow	yellow
Ch. B-	/	orange
Ch. Z	blue	blue
Ch. Z-	/	white
 	shield	shield

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# ETMA 1 / 2 MAGNETIC INCREMENTAL LINEAR SENSOR

#### MAIN FEATURES

Incremental linear system based on magnetic principle without wear thanks to no-contact technology. Thanks to high IP rating ETMA is suitable for harsh environment applications such as marble and glass working machines, washing systems machines.

- 0,01 mm max resolution (after quad eval)
- Power supply up to +28 VDC with several electronic interfaces available
- Up to 4 m/s travel speed
- · IP 67 as protection grade
- · Cable output, connector available on cable end





ORDERING CODE	ETMA	1	Z	5	Р	S	PR3	. XXX
magnetic incre	SERIES mental linear sensor ETMA							
	RES 0	<b>SOLUTION</b> 0,1 mm 1 ,04 mm 2						
	1	ZEI without ze with ze	RO PULSE ro pulse S ro pulse Z					
	(with L) (with L or PC electroni	electronic ic interface	<b>POWER</b> interface) 5 e) 8 24 V 1 5 28 V 1	<b>SUPPLY</b> 5 V DC 5 DC 8/24 DC 5/28				
		(AEIC-	ELECTI -7272) prote	RONIC IN pus cted push	<b>TERFACE</b> sh-pull P 1-pull PC			
	I	power sup	ply 5/28 V -	line output RS E	e driver L S-422 RS NCLOSUR	E RATING		
					ca	IP 67 S OUTP ble length	<b>UT TYPE</b> 3 m PR3	
	pro	eferred cai	ble length 3	/6/10/	20 m, oth	ers on requ	<i>iest</i>   sustom ver	VARIANT sion XXX





## ETMA 1 / 2



**Mechanical tolerances** 



dimensions in mm

ELECTRICAL SPECIFICATIONS				
Resolution	$\begin{array}{l} \text{ETMA1}=0,1 \text{ mm (0,025 mm after quad eval)} \\ \text{ETMA2}=0,04 \text{ mm (0,01 mm after quad eval)} \end{array}$			
Zero pulse	ETMA1 = every 5 mm ETMA2 = every 2 mm			
Power supply	$\begin{array}{l} 5 = 4,5 \ldots 5,5 \mbox{ V DC} \\ 5/28 = 4,75 \ldots 29,4 \mbox{ V DC} \\ 8/24 = 7,6 \ldots 25,2 \mbox{ V DC} (reverse polarity protection) \end{array}$			
Current consumption without load	30 mA max			
Max load current	20 mA / channel			
Output type *	push-pull line driver HTL / RS-422			
Linearity error	± 0,025 mm (ETMA 1) ± 0,01 mm (ETMA 2)			
Travel speed	4 m/s			
Electromagnetic compatibility	IEC 61000-6-2 IEC 61000-6-4			

\*output levels according to power supply, for further details please see under Technical basics section

# MECHANICAL SPECIFICATIONS

Enclosure rating	IP 67 (IEC 60529)
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 10 2000 Hz (IEC 60068-2-6)
Housing material	anodized aluminium
Fixing	n. 2 holes ø 3,5 mm
Operating temperature	-10° +60°C (+14° +140°F)
Storage temperature	-25° +70°C (-13° +158°F)
Working distance from magnetic tape	ETMA 1 < 1,5mm with magnetic tape protection ETMA 1 < 2mm without cover ETMA 2 < 0,5mm with magnetic tape protection ETMA 2 < 1mm without cover
Weight	150 g (5,29 oz)



CONNECTIONS		
Function	Cable output Push-pull	Cable output Line driver
+V DC	red	red
0 V	black	black
Ch. A	green	green
Ch. A-	/	brown
Ch. B	yellow	yellow
Ch. B-	/	orange
Ch. Z	blue	blue
Ch. Z-	/	white
<u>+</u>	shield	shield





· Magnetic tape to be used with ETMA

2 mm or 5 mm pole pitch
High pole accuracy
Available in reels up to 50 m

· Easy mounting due to premounted double side adhesive

MAIN FEATURES

**ORDERING CODE** 

# EBMA MAGNETIC TAPE



separate the code with a dash -

TAPE LENGTH from 0,5 m to 50 m 10

VARIANT custom version XXX

# EBM A 1 10 . XXX SERIES magnetic tape EBM TAPE TYPE standard magnetic tape A Image: Comparison of the second second

EBM



dimensions in mm

GENERAL SPECIFICATIONS			
Operating temperature	-40° +100°C (-40° +212°F)		
Accuracy	± 0,04 mm/m		
Linear expansion coefficient	17* 10 <sup>-6</sup> m/K		
Bending radius	100 mm min		





## **GENERAL SPECIFICATIONS**

As shown in the figure below, Eltra magnetic tape is composed by three layers:

1 - a flexible magnetic tape made of ferrite bonded into a nitrile rubber matrix;

2 - a stainless steel tape used to create a shield against any external magnetic fluxes and other external agents. Furthermore it's glued to the upper layer in order to give the correct mechanical consistency to the magnetic tape:

3 - a steel tape, magnetically transparent and with the function to protect mechanically the magnetic layer, it is the most rigid part and therefore is supplied separately due to transport and application needs. It must be sticked on layer 1 by the user.



To prevent damage from possible internal stresses in the magnetic tapee rolled up with magnetic layer facing outwards, with a minimum internal diameter of 300 mm.

## TIPS TO STICK ON THE MAGNETIC TAPE

#### Fixing pressure.

The magnetic tape is adhesive. Therefore it is important optimum contact between surfaces for right use. A good pressure must be uniformly applied to guarantee a perfect result.

#### Glueing temperature.

In order to guarantee optimal sticking it is recommended a surface temperature between 20 °C and 35 °C. Maximum adhesion is obtained after 72 hours at temperature of 21 °C. Please do not apply magnetic tape when surface temperature is lower than 10 °C.

#### Application materials.

Magnetic tape must be placed on dry, smooth and clean surfaces. Surfaces must be cleaned with aqueous solution. Matallic surfaces like brass, copper etc. must be protected to prevent possible oxidation.

CHEMICAL AGENTS AND MAGNETIC TAPE BEHAVIOUR					
Null effect chemicals	Medium effec chemicals	Strong effect chemicals			
motor oil	JP-4 fuel	aromatic hydrocarbons (benzene, toluene, xylene, trichloroethylene, freon 10)			
transmission oil	gasoline	ketones (acetone)			
ATF (automatic transmission fluid)	heptane	mineral acids (hydrochloric, sulphuric, nitric, pho- sphoric, boric)			
hydraulic oil	alcohols				
kerosene					
antifreeze					
detergents, disinfectants (Clorox®)					
turpentine					
water					
salt spray					







#### MAIN FEATURES

Rope encoder series with Dyneema rope available for lengths up to 4 m. The applied encoder could be incremental or absolute. Perfectly suitable also for harsh enviroments, thanks to its high mechanical strength. It can be used in wide range of applications such as: vertical storehouses, presses, extruders, etc.



#### **ORDERING CODE**

#### FE 1500 A .XXX

eyelet A

VARIANT custom version XXX

# SERIES rope encoder for linear measures FE WORKING STROKE 1,5 m 1500 4 m 4000 TYPE OF ROPE END

The encoder you wish to apply to the FE model needs to be ordered separately. The F letter will be placed before the standard ordering code.

FE 4000

 $\pm 2 \text{ mm}$ 

220 mm

#### Example:

- 1) encoder model EH 30 M ordering code: FEH30M300S8/24P6X6PR
- 2) encoder model EL 53 B ordering code: FEL53B1100S5/28P6X3MR
- 3) encoder model EAM 53 B ordering code: FEAM53B16/4096G8/28PPX6X3MER

# Complete ordering code example: FE1500A-FEH30M300S8/24P6X6PR

#### For encoder specifications, refer to single product datasheet :

- EH 30 M see EH 30 M EH 30 MH encoder
- EL 53 B see EL ER 53 encoder

**GENERAL SPECIFICATIONS** 

- EAM 53 B see EAM 58 - 63 solid shaft encoder

Model

Linearity error Drum circumference

MECHANICAL SPECIFICATIONS			
Max speed	0,85 m/s		
Pull-out force required	≥ 9 N		
Enclosure rating	depends on encoder IP		
Shock	50 G, 11 ms (IEC 60068-2-27)		
Vibration	10 G, 10 2000 Hz (IEC 60068-2-6)		
Housing material	painted aluminum		
Rope material	Dyneema®		
Operating temperature	-10° +60°C (+14° +140°F)		
Storage temperature	-25° +70°C (-13° +158°F)		
Weight	500 g (17,64 oz) mod. 1500 1100 g (38,80 oz) mod. 4000		

Mechanical resolution [mm] = Drum circumference [mm] / Encoder pulses [ppr o singleturn resolution]

FE 1500

± 0,75 mm

120 mm





## FE 1500

\* dimensions with EH30M encoder



## FE 4000

\* dimensions with EH30M encoder



# FEL 53 B

**\*** incremental encoder application



dimensions in mm

Eltra

FEAM 53 B

★ multiturn absolute encoder application







#### MAIN FEATURES

Rope encoder series with steel rope available for lengths up to 15 m. The attached encoder can be incremental or absolute. Perfectly suitable also for harsh environments, thanks to its excellent mechanical strength. It can be used in wide range of applications such as: vertical warehouses, presses, extruders, etc.



# **ORDERING CODE**

# FES 3000 A .XXX

VARIANT custom version XXX

#### SERIES rope encoder for linear measures FES WORKING STROKE 3 m 3000 6 m 6000 15 m 15000 UUTPUT TYPE horizontal output A

Incremental or absolute (model 58B) must be ordered together. Please add letter F before standard encoder ordering code.

Example:

1) with incremental encoder ordering code will be : FER58B ...

2) with absolute multiturn encoder ordering code will be : FEAM58BR ....

3) with absolute Profinet multiturn encoder ordering code will be : FAAM58B ...

Complete ordering code example: **FES3000A-FER58B** ...

#### **FES 3000**







## **FES 6000**



**FES 15000** 



# 188 $\bigcirc$ ( 85 Æ $\bigcirc$ $\bigcirc$ 51

dimensions in mm

# MECHANICAL SPECIFICATIONS

Model	FES 3000 FES 6000		FES 15000	
Max length measurement	3 m	6 m	15 m	
Drum circumference	200 mm	200 mm	500 mm	
Wire diameter	0,87 mm	0,54 mm	0,87 mm	
Repeat accuracy	± 0,	15 mm	± 0,25 mm	
Max speed	0,8 m/s	3 m/s	2,4 m/s	
Pull-out force required	≥ 3 N	≥ 8 N	≥ 15,5 N	
Housing material	aluminu	aluminium die casting		
Rope material	S	steel rope, synthetically coated		
Enclosure rating				
Operating temperature	-40° +80°C (-40° +176°F)	-40° +80°C (-40° +176°F) -20° +80°C (-4° +176°F)		
Weight	350 g (12,35 oz) + encoder	700 g (24,69 oz) + encoder	2500 g (88,18 oz) + encoder	
(EL-ER 58B) L*	95 mm	140 mm	114 mm	
(EAM 58BR) L*	109 mm	154 mm	128 mm	
(EAM 58B PROFIBUS) L*	135 mm	180 mm	154 mm	
(EL-ER 58B) C*	58 mm	70 mm	99,5 mm	
(EAM 58BR) C*	70 mm	82 mm	100,5 mm	
(EAM 58B PROFIBUS) C*	98 mm	110 mm	127,2 mm	





#### Installation notes

A 5 mm wire extension is recommended before the measurement

starting point. This prevents the wire snapping back to the stop on rewinding. Wire should be pulled out straight in line with wire outlet.





#### MAIN FEATURES

EPLA is an absolute linear potentiometer assuring great reliability even in tough applications with heavy vibrations and shocks.

The groove on the enclosure of the transducer represents an excellent alternative to the usual system of fastening with brackets.

Installation is also made simpler by the absence of variations on the electrical output signal outside of the theoretical electrical stroke.

EPLA is the right solution in machinery for material processing such as injection presses for plastic, rubber and so on.















dimensions in mm

- · fixing kit (brackets, screws) included
- · female connector not included, for ordering P/N please refer to Accessories section

CONNECTIONS							
Function	Cable output	3 pin C3 output	4 pin C4 output	5 pin C5 output			
+	blue	3	3	3			
-	brown	1	1	1			
output	yellow	2	2	2			
nc	/	/	/	/			
nc	/	/	/	/			
÷	shield	/	<u>+</u>	/			

C3 connector (3 pin)

solder side view FV





Ē



C5 connector (5 pin)

DIN 45322

Mounting with screw M5 ISO4017-DIN933



ELECTRICAL SPECIFICATIONS				
Resolution	virtually infinite			
Independent linearity	± 0,05 %			
Repeatability	0,01 mm			
Resistance tolerance	± 20 %			
Recommended cursor current	< 0,1 µA			
Resistence thermal coefficient	-200 200 ppm / °C typical			
Output voltage temperature coefficient	≤ 5 ppm / °C			
Power dissipation	3 W at 40 °C / 0 W at 120 °C			
Max cursor current	10 mA			
Applicable voltage	60 V DC max			
Electrical insulation	$>$ 100 M $\Omega$ , 500 VDC, 1 bar, 2 s			
Dielectric strenght	$<$ 100 $\mu\text{A},$ 500 VAC, 50 Hz, 1 bar, 2 s			

Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\leq 0,1 \ \mu A$ .

#### MECHANICAL SPECIFICATIONS

Stroke	50 - 100 - 150 - 200 - 300 - 350 - 400 - 450 - 500 - 600 - 750 - 900 mm
Useful electric stroke (EEU) (+ 3 / - 0 mm)	see model (mm)
Theoretical electric stroke (EET) (±1 mm)	EEU + 3 mm (50 150), EEU + 4 mm (200 300), 355 mm (350), 406 mm (400), 457 mm (450), 508 mm (500), 609 mm (600), 762 mm (750), 914 mm (900)
Mechanical stroke (EM)	EEU + 9 mm (50 150), EEU + 10 mm (200 300), 361 mm (350), 412 mm (400), 463 mm (450), 518 mm (500), 619 mm (600), 772 mm (750), 924 mm (900)
Resistance (on the EET)	5 kΩ (50 600) 10 kΩ (750 900)
Case length (LP)	EEU + 63 mm (50 150), EEU + 64 mm (200 300), 415 mm (350), 466 mm (400), 517 mm (450), 572 mm (500), 673 mm (600), 826 mm (750), 978 mm (900)
Travel speed	10 m/s max
Acceleration	200 m/s <sup>2</sup> max
Enclosure rating	X = IP 60 / S= IP 65 (IEC 60529)
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)
Displacement force	3,5 N typical (IP 60) / 15 N typical (IP 65)
Housing material	anodized aluminium / Nylon 66 G
Pull shaft material	1.4305 / AISI 303 stainless steel
Mounting	brackets with variable center-to-center distance or M5 ISO4017 - DIN933 screw
Life	$>25\ x\ 10^6\ m$ strokes or $>100\ x\ 10^6\ manoeuvres$
Operating temperature	-30° +100°C (-22° +212°F)
Storage temperature	-50° +120°C (-58° +248°F)

#### Installation warning instructions:

connect the transducer according to the reported connections
 DO NOT use it as a variable resistance

· the transducer calibration has to be done setting the stroke in order to have an output signal between 1% and 99% of the voltage level







#### MAIN FEATURES

EPLB is an absolute linear potentiometer transducer.

Mechanical mounting is made simpler by the presence of two spherical joints on the two sides and by the enclosure's cylindrical shape.

The main characteristic is the absence of variations on the electrical output signal outside of the theoretical electrical stroke.

Thanks to its robustness and precision EPLB represents a great solution in most mechanical application for automation.



DRDERING CODE	EPLB	300	S	5	Р	R	
	SERIES cylindrical linear potentiometer model EPLB mm from 5 see table for stroke av E	STROKE 50 to 750 vailability NCLOSURI	E <b>RATING</b> IP 65 S <b>TRAVI</b> max speed	E <b>L SPEED</b> d 5 m/s 5			
		C Din M16 C	able (star   43650-C )IN 45322	OUTF ndard leng 3 pin conr 4 pin conr 5 pin conr (	PUT TYPE th 1 m) P nector C3 nector C4 nector C5 DUTPUT DII	<b>RECTION</b> radial R	





**EPLB** 





C5 connector (5 pin)

DIN 45322

solder side view FV

dimensions in mm

· female connector not included, for ordering P/N please refer to Accessories section

CONNECTIONS							
Function	Cable output	3 pin C3 output	4 pin C4 output	5 pin C5 output			
+	blue	3	3	3			
-	brown	1	1	1			
output	yellow	2	2	2			
nc	/	/	/	/			
nc	/	/	/	/			
÷	shield	/	<del></del>	/			

solder side view FV



C3 connector (3 pin) C4 connector (4 pin) DIN 43650-C solder side view FV





ELECTRICAL SPECIFICATIONS				
Resolution	virtually infinite			
Independent linearity	± 0,05 %			
Repeatability	0,01 mm			
Resistance tolerance	± 20 %			
Recommended cursor current	< 0,1 µA			
Output voltage temperature coefficient	≤ 1,5 ppm / °C			
Power dissipation	3 W at 40 °C / 0 W at 120 °C			
Max cursor current	10 mA			
Applicable voltage	60 V max			
Electrical insulation	$>$ 100 M $\Omega$ , 500 VDC, 1 bar, 2 s			
Dielectric strenght	< 100 µA, 500 VAC, 50 Hz, 1 bar, 2 s			

Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\leq 0,1 \ \mu$ A.

#### **MECHANICAL SPECIFICATIONS** 50 - 100 - 150 - 200 - 300 - 400 - 450 - 500 -Stroke 600 - 750 mm **Useful electric stroke** see model (mm) (EEU) (+3/-0 mm) EEU + 3 mm (50 ... 150), EEU + 4 mm (200 ... 300), 406 mm (400), 457 mm (450), 508 mm (500), 609 mm (600), 762 mm (750) Theoretical electric stroke (EET) (±1 mm) EEU + 9 mm (50 ... 150), EEU + 10 mm (200 ... 300), 412 mm (400), 463 mm (450), 518 mm (500), Mechanical stroke (EM) 619 mm (600), 772 mm (750) 5 kΩ (50 ... 600) Resistance (on the EET) 10 kΩ (750) EEU + 129 mm (50 ... 150) EEU + 130 mm (200 ... 300), 538 mm (400), 589 mm (450), 664 mm (500), Case length (LP) 765 mm (600), 918 mm (750) EEU + 177 mm (50 ... 150), EEU + 178 mm (200 ... 300), 586 mm (400), 637 mm (450), 712 mm (500), 813 mm (600), 966 mm (750) Minimum interaxis length (A)

Travel speed	5 m/s max
Enclosure rating	IP 65 (IEC 60529)
Shock	50 G, 11 ms (IEC 60068-2-27)
Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)
Displacement force	≤ 15 N
Moving angle	± 25° max
Housing material	anodized aluminium / Nylon 66 G
Rod material	1.4305 / AISI 303 stainless steel
Mounting	n° 2 selfloading and selfaligning ball-joints
Life	$> 25 \times 10^6$ m strokes or $> 100 \times 10^6$ manoeuvres
Operating temperature	-30° +100°C (-22° +212°F)
Storage temperature	-50° +120°C (-58° +248°F)

Installation warning instructions:

connect the transducer according to the reported connections

DO NOT use it as a variable resistance

the transducer calibration has to be done setting the stroke in order to have an output signal between 1% and 99% of the voltage level



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#### MAIN CHARACTERISTICS

EPLC is an absolute linear potentiometer transducer without internal rod. This transducer is characterized by a cursor with integrated coupling sliding on the axis. The main characteristic is the absence of variations on the electrical output signal outside of the theoretical electrical stroke.



ORDERING CODE	EPLC	500	X	4	<b>C4</b>	A
	SERIES rodless linear potentiometer model EPLC mm from 10 see table for stroke an E	STROKE 0 to 1500 /ailability :NCLOSUR m m DII	E RATING IP 40 X TRAVI nax speed ax speed 1 V 43650-A	EL SPEED 10 m/s 4 0 m/s 10 0UTI 4 pin cont	PUT TYPE nector C4	
		mio		(	DUTPUT DI	RECTION axial A







ELECTRICAL SPECIFICATIONS				
Resolution	virtually infinite			
Independent linearity	± 0,05 %			
Repeatability	0,01 mm			
Resistance tolerance	± 20 %			
Recommended cursor current	< 0,1 µA			
Resistance temperature coefficient	-200 200 ppm / °C typical			
Output voltage temperature coefficient	≤ 5 ppm / °C typical			
Power dissipation	3 W at 40 °C / 0 W at 120 °C			
Max cursor current	10 mA max			
Applicable voltage	60 V max			
Electrical insulation	$> 100 \text{ M}\Omega$ , 500 VDC, 1 bar, 2 s			
Dielectric strenght	< 100 µA, 500 VAC, 50 Hz, 1bar, 2 s			

MECHANICAL SPECIFICA	MECHANICAL SPECIFICATIONS					
Stroke	100 - 150 - 200 - 300 - 400 - 500 - 600 - 700 - 850 - 900 - 1000 - 1250 - 1500 mm					
Useful electric stroke (EEU) (+3/-0 mm)	see model (mm)					
Theoretical electric stroke (EET) (±1 mm)	103 mm (100), 153 mm (150), 204 mm (200), 305 mm (300), 406 mm (400), 509 mm (500), 611 mm (600), 713 mm (700), 865 mm (850), 915 mm (900), 1017 mm (1000), 1271 mm (1250), 1521 mm (1500)					
Mechanical stroke (EM)	EET + 10mm (100 1500)					
Resistance (on the EET)	5 kΩ (100 300) 10 kΩ (400 1000) 20 kΩ (1250 1500)					
Case length (LP)	EET + 150mm (100 1500)					
Travel speed	4 = 4 m/s max 10 = 10 m/s max					
Acceleration	200 m/s <sup>2</sup> max					
Enclosure rating	IP 40 (IEC 60529)					
Shock	50 G, 11 ms (IEC 60068-2-27)					
Vibration	20 G, 5 2000 Hz (IEC 60068-2-6)					
Displacement force	≤ 1,2 N max					
Housing material	anodized aluminium / Nylon 66 G 25					
Mounting	brackets with variable center-to-center distance with M6 screw ISO4017 - DIN933					
Operating temperature	-30° +100°C (-22° +212°F)					
Storage temperature	-50° +120°C (-58° +248°F)					

## **ELECTRICAL CONNECTIONS**



#### Installation warning instructions:

connect the transducer according to the reported connections

- DO NOT use it as a variable resistance
- the transducer calibration has to be done setting the stroke in order to have an output signal between 1% and 99% of the voltage level

dimensions in mm

· fixing kit (brackets, screws, grower) included

· female connector not included, for ordering P/N please refer to Accessories section

CONNECTIONS			
Function	Cable output	4 pin C4 output	5 pin C5 output
+	blue	3	3
-	brown	1	1
output	yellow	2	2
nc	/	/	/
nc	/	/	/
÷	shield	÷	/



C5 connector (5 pin) DIN 45322 solder side view FV

(4) (2

5

MF



Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\le 0,1~\mu{\rm A}$ 







#### MAIN CHARACTERISTICS

EPLT is an absolute linear potentiometer transducer.

This model is characterized by the absence of cursor and the presence of a sensing system, composed by a moving rod, stainless steel sphere mounted on a threaded tip with a spring.

This transducer is suitable for applications where short strokes are requested.

The presence of the spring assures an automatic head positioning making this device suitable for being used in precise applications on cams or to control products coming from automatic production line. EPLT is also characterized by the absence of variations on the electrical output signal outside of the theoretical electrical stroke.



ORDERING CODE	EPLT	100	X	10	Р	A
	SERIES linear potentiometer with ball tip EPLT 10 / 25 / 50 / please contact our offices for othe E	STROKE 75 / 100 er strokes NCLOSUR m: C M16 I	E RATING IP 40 X TRAVE ax speed 1 able (star DIN 43322	i <b>L SPEED</b> 0 m/s 10 <b>OUTF</b> dard leng 5 pin conr (	PUT TYPE th 1 m) P nector C5 DUTPUT DI	RECTION
						axiai A





EPLT





dimensions in mm

· fixing kit (brackets, M4x10 screws, washer) and tip with ball included

female connector not included, for ordering P/N please refer to Accessories section

CONNECTIONS		
Function	Cable output	5 pin C5 output
+	blue	3
-	brown	1
output	yellow	2
nc	/	/
nc	/	/
<u>+</u>	shield	/



Important: data are valid if the transducer is used as a ratiometric device with a maximum applicable current  $\le$  0,1  $\mu\rm A$ 

ELECTRICAL SPECIFICATIONS						
Resolution	virtua	virtually infinite				
Stroke	mm	10	25	50	75	100
Independent linearity	%	± 0,3	± 0,2	± 0,1	± 0,1	± 0,1
Resistance tolerance	± 20 '	± 20 %				
Recommended cursor current	< 0,1 µA					
Output voltage temperature coefficient	< 1,5 ppm / °C					
Power dissipation at 40 °C (0 W at +120 °C)	w	0,2	0,6	1,2	1,8	2,4
Max cursor current	10 mA max					
Max applicable voltage	V	14	25	60	60	60
Electrical insulation	$> 100 \text{ M}\Omega$ , 500 VDC, 1 bar, 2 s					
Dielectric strenght	renght < 100 μA, 500 VAC, 50 Hz, 1bar, 2 s					

# MECHANICAL SPECIFICATIONS

Stroke	mm	10	25	50	75	100
Useful electric stroke (EEU) (+1/-0 mm)	mm	10	25	50	76	101
Theoretical electric stroke (EET) (±1 mm)	mm	11	26	51	76	101
Mechanical stroke (EM)	mm	15	30	55	81	106
Resistance (on EET)	kΩ	1	1	5	5	5
Case length (LP)	mm	48	63	88	114	139
Sensing probe length	mm	32	32	40	40	40
Additional length (D)	mm	-	-	-	5	11
Total length (LT)	mm	108	138	196	251	307
Travel speed	10 m/	s max				
Enclosure rating	IP 40	(IEC 6052	29)			
Shock	50 G,	11 ms (IE	EC 60068	-2-27)		
Vibration	20 G,	5 2000	) Hz (IEC	60068-2-	-6)	
Displacement force	≤ 4 N					
Housing material	anodized aluminium / Nylon 66 G 25					
Rod material	1.4305 / AISI 303 stainless steel					
Mounting	brackets with variable center-to-center distance					
Life	$> 25 \times 10^6$ m strokes or $> 100 \times 10^6$ operations					
Operating temperature	-30°.	-30° +100°C (-22° +212°F)				
Storage temperature	-50° +120°C (-58° +248°F)					

# ELECTRICAL CONNECTIONS



#### Installation warning instructions:

· connect the transducer according to the reported connections

• DO NOT use it as a variable resistance

 the transducer calibration has to be done setting the stroke in order to have an output signal between 1% and 99% of the voltage level



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# EMSPA LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH ANALOGUE OUTPUT

#### MAIN CHARACTERISTICS

EMSPA is an absolute linear magnetostrictive transducer with analog interface. Thanks to the absence of electrical contact on the enclosure there is no issue of wear and deterioration during working life. Magnetostrictive technology guaranties great performances of speed and accuracy.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.

ORDERING CODE	EMSPA	500	S	20D	10	Р	A
	SERIES Inear magnetostrictive transducer with analogue output EMSPA mm from 5 see table for stroke and 0 10 0 10 VDC 0 10 VDC 0 10 VDC / 2 cursi 4 20 mA 4 20 mA / 2 cursi	STROKE 0 to 1500 vailability ENCLOSUR / DC / 1 cursor ors (min. s 4 2 / 1 cursor ors (min. s	E RATING IP 67 S OUTPU rrsor (stank stroke 400 0 mA / 1 c position/s stroke 400 m m M16 M16	T SIGNAL lard) 10S peed 10P mm) 10D ursor 20S peed 20P mm) 20D TRAVI ax speed 1 sable (star M12 M12 DIN 453226	EL SPEED 0 m/s 10 0 UTF dard leng 5 pin com 8 pin com 8 pin com 8 pin com	PUT TYPE th 1 m) P nector S5 nector C6 nector C8 DUTPUT D1	RECTION
							alial A I







EMSPA



dimensions in mm

· brackets, cursors and female connector not included, for ordering P/N please refer to Accessories section

ELECTRICAL SPECIFICA	TIONS		MECHANICAL SPECIFIC	ATIONS
Resolution	16 bit (max electrical no	oise 5 mVpp)	<b>.</b>	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 -
Output signal	0 10 VDC	4 20 mA	Stroke	500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm
Output alarm value	10,5 VDC	21 mA	Electric stroke (EE)	see model (mm)
Output max value	12 VDC	30 mA	Overall dimension (LT)	EE + 154 mm
Power supply	19,2 28,8 VDC		Enclosure rating	IP 67 (IEC 60529)
Power ripple	1 Vpp max		Detected measurement	displacement / speed
Current consumption	70 mA max	90 mA max	Travel speed	10 m/s max
Output load	5 kΩ	< 500 Ω	Acceleration	100 m/s² max
Output ripple	< 5  mVpp $\leq \pm 0.01 \% \text{ FS (min } \pm 0.060 \text{ mm) typical with}$		Speed measurament range	min 0 0,1 m/s max 0 10 m/s
	sliding cursor	ting ouroor	Speed accuracy	< 2%
Indipendent linearity	$\leq \pm 0.02$ % FS with hoat (working distance 2 5	i mm)	Shock	100 G, 11 ms, single shock (IEC 60068-2-27)
	$\leq \pm 0.04$ % FS with float (working distance 5 7		Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)
Reneatability			Housing material	anodized aluminium / Nylon 66 G 25
Hysteresis	< 0.01 mm		Cursor type	sliding or floating cursor
	0.5 ms (50 300)		Temperature coefficient	0,005 % FS / °C
Sampling time	1 ms (350 1100)		Operating temperature	-30° +75°C (-22° +167°F)
	1,5 ms (1200 1500)		Storage temperature	-40° +100°C (-40° +212°F)
Protection against overvoltage	yes			
Protection against polarity inversion	yes			
Protection against power supply on output	yes			
Electrical insulation	500 VDC			
Electromagnetic compatibility	according to 2014/30/E	U directive		



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CONNECTIONS					
Function	Cable output	S5 5 pin M12 connector	S8 8 pin M12 connector	C6 6 pin M16 connector	C8 8 pin M16 connector
+ V DC	brown	5	7	5	7
OV	white	4	6	6	8
Output cursor 1 0 10 V 4 20 mA	grey	1	5	1	5 (1*)
OV cursor 1	pink	2	1	2	2
Inverse output cursor 1 Output cursor 2 Output speed 10 0 V 20 4 mA	yellow	3	3	3	3
OV Output cursor 1 Output cursor 2 Output speed	pink	2	2	4	6

The transducer enclosure has to be connected to ground only on the control system side by the cable shield, to guarantee the correct electrical insulation of the transducer from the machine, always assemble the brackets using the plastic washers included.

S5 connector (5 pin) M12 A coded solder side view FV

S8 connector (8 pin) M12 A coded solder side view FV







C8 connector (8 pin) DIN 45326 solder side view FV

(8)

#### Installation example with two cursors



For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel).

The installation kit provides two screws, two nuts and two washers (all made of brass). The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 7 mm.

#### Current output application example









# LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH ANALOGUE OUTPUT

#### MAIN CHARACTERISTICS

EMSPB is an absolute linear magnetostrictive transducer with analogue interface. Thanks to the absence of electrical contact on the enclosure there is no issue of wear and deterioration during working life.

Magnetostrictive technology guaranties great performances of speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.







#### **EMSPB**



dimensions in mm

· brackets, cursors and female connector not included, for ordering P/N please refer to Accessories section

#### MECHANICAL SPECIFICATIONS

Stroke	50 - 100 - 150 - 200 - 225 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1300 - 1400 - 1500 mm			
Electric stroke (EE)	see model (mm)			
Overall dimension (LT)	EE + 154 mm			
Enclosure rating	IP 65 (IEC 60529)			
Detected measurement	displacement			
Travel speed	10 m/s max			
Acceleration	100 m/s² max			
Shock	100 G, 11 ms, single shot (IEC 68000-2-27)			
Vibration	12 G, 10 2000 Hz (IEC 68000-2-6)			
Housing material	anodized aluminium / Nylon 66 G 25			
Cursor type	floating cursor			
Temperature coefficient	≤ 0,01 % FS / °C (min. 0,015 mm / ° C)			
Operating temperature	-20° +75°C (-4° +167°F)			
Storage temperature	-40° +100°C (-40° +212°F)			

ELECTRICAL SPECIFICATIONS				
Resolution	virtually infinite			
Output signal	0,1 10,1 VDC 4 20 mA			
Output alarm value	10,5 V DC	21 mA		
Output value max	12 V DC	30 mA		
Power supply	19,2 28,8 VDC			
Power ripple	1 Vpp max			
Current consumption	35 mA max	60 mA max		
Output load	≥ 10 kΩ	50 500 Ω		
Indipendent linearity	$\pm$ 0,04% FS max (min $\pm$ 0,09 mm)			
Repeatability	≤ 0,01 mm			
Hysteresis	≤ 0,02 mm			
Sampling time	1 ms (50 600) 1,5 ms (650 900) 2 ms (1000 1300) 3 ms (1400 1500)			
Protection against overvoltage	yes			
Protection against polarity inversion	yes			
Protection against power supply on output	yes			
<b>Electrical insulation</b>	50 VDC			
Electromagnetic compatibility	according to 2014/30/EU directive			

#### Installation notes

For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel).

The installation kit provides two screws, two nuts and two washers (all made of brass).

The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 5 mm.



CONNECTIONS

Function

+V DC

0 V

Output

OV output

÷

M12 connector (5 pin) M12 A coded solder side view FV

C4 4 pin

connector

3

1

2

1

shield

S5 M12 5 pin

connector

5

4

1

2

/





#### Current output application example



Note: connect as close as possible to transducer







# **EMSPS** LINEAR MAGNETOSTRICTIVE TRANSDUCER WITH SSI OUTPUT

#### MAIN CHARACTERISTICS

EMSPS is an absolute linear magnetostrictive transducer featuring a digital RS-422 SSI compliant output.

The main characteristic of magnetostrictive transducers is the absence of electric contact on the enclosure there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.











dimensions in mm

· brackets, cursors and female connector not included, for ordering P/N please refer to Accessories section

ELECTRICAL SPECIFICA	TIONS	MECHANICAL SPECIFIC	ATIONS
Resolution	2 - 5 - 10 - 20 - 40 $\mu$ m ≤ ± 0.01% FS (min ± 0.060 mm) typical	Stroke	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1100 - 1200 - 1400 - 1400 - 1500 mm
Indipendent linearity	with sliding cursor		1100 - 1200 - 1300 - 1400 - 1500 IIIII
	$\leq \pm 0.02\%$ FS typical with floating cursor	Electric stroke (EE)	see model (mm)
Repeatability	< 0,01 mm	Overall dimensions (LT)	EE + 154 mm
Hysteresis	$\leq \pm 0,005\%$ FS (min 0,010 mm)	Enclosure rating	IP 67 (IEC 60529)
Power supply	10 32 VDC	Detected measurement	displacement
Power ripple	1 Vpp max	Scale orientation	increasing
Max load current	50 mA max	Travel speed	10 m/s max
Output type	RS-422	Acceleration	100 m/s <sup>2</sup> max
SSI output code	binary or gray	Shock	100 G, 11 ms, single shot (IEC 68000-2-27)
Clock frequency	50 kHz 1 MHz	Vibration	12 G, 10 2000 Hz (IEC 68000-2-6)
SSI monostable time (Tm)	16 µs	Housing material	anodized aluminium / Nylon 66 G 25
SSI frame	21 / 24 / 25 bit data length	Cursor type	sliding or floating cursor
Counting direction	increase	Temperature coefficient	20 ppm FS / °C
Protection against	Ves	Operating temperature	-30° +90°C (-22° +194°F)
overvoltage	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Storage temperature	-40° +100°C (-40° +212°F)
Protection against polarity inversion	yes		
Self-resetting internal fuse	yes		
<b>Electrical insulation</b>	500 VDC (+VDC / earth)		
Electromagnetic compatibility	according to 2014/30/EU directive	_	

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CONNECTIONS				
Function	Cable output	S8 8 pin M12 connector	C6 6 pin M16 connector	C8 8 pin M16 connector
+ V DC	blue / white	7	5	7
0V	blue	6	6	6
data +	orange / white	2	2	2
data -	orange	5	1	5
clock +	green / white	3	3	1
clock -	green	1	4	3

The transducer enclosure and cable shield have to be connected to ground on both sides.



## SSI BLOCK DIAGRAM



SSI output goes to 0 if the echo is absent (magnet out of measurement range or internal device error)

SSI CABLE LENGTH					
Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m
Baud rate	1 Mbaud	400 kbaud	300 kbaud	200 kbaud	100 kbaud

#### Installation example with two cursors



For multi-cursor model, the cursors have to work in the same conditions of distance and temperature. Cursors must be installed on a support made of non-magnetic material (like brass, aluminium or AISI316 stainless steel).

The installation kit provides two screws, two nuts and two washers (all made of brass).

The cursor must be installed with maximum attention to horizontal alignment with the transducer axis (maximum tolerance is  $\pm 2$  mm), distance from the transducer surface has to be within the range from 2 to 7 mm.







# LINEAR MAGNETOSTRICTIVE ROD TRANSDUCER WITH ANALOGUE OUTPUT

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#### MAIN CHARACTERISTICS

EMSSA is an absolute linear magnetostrictive transducer featuring an analogue interface. Main characteristics of magnetostrictive transducers is the absence of electric contact on the enclosure there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure. This series has been designed for being mounted internally to high applications (350 bar, 500 bar peak) such as hydraulic or pneumatic cylinders.





UNI EN ISO 9001:2008





#### EMSSA



dimensions in mm

· OR 15,4 x 2,1 (mod.H) / OR 16,36 x 2,21 (mod.I) included

· Cursors and female connector not included, for ordering P/N please refer to Accessories section

ELECTRICAL SPECIFICATIONS				
Resolution	16 bit (max electrical no	oise 5 mVpp)		
Output signal	0 10 VDC	4 20 mA		
Output alarm value	10,5 VDC	21 mA		
Output value max	12 VDC	30 mA		
Power supply	19,2 28,8 VDC			
Power ripple	1 Vpp max			
Current consumption	70 mA max 90 mA max			
Output load	5 kΩ	< 500 Ω		
Output ripple	< 5 mVpp			
Indipendent linearity	$\leq \pm 0.02\%$ FS (min $\pm 0.060$ mm)			
Repeatability	< 0,01 mm			
Hysteresis	< 0,01 mm			
Sampling time	0,5 ms (mod. 50 200) 1 ms (mod. 400 1000) 1,5 ms (mod. 1250 1500)			
Protection against overvoltage	yes			
Protection against polarity inversion	yes			
Protection against power supply on output	yes			
Electrical insulation	500 VDC			
Electromagnetic compatibility	according to 2014/30/EU directive			

MECHANICAL SPECIFICATIONS			
Stroke	50 - 100 - 150 - 200 - 250 - 300 - 350 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1250 - 1500 mm		
Electric stroke (EE)	see model (mm)		
Overall dimensions (LT)	EE + 176,2 mm (mod. 50 900) EE + 181,2 mm (mod. 1000 1500)		
Enclosure rating	IP 67 (IEC 60529)		
Detected measurement	displacement		
Travel speed	10 m/s max		
Acceleration	100 m/s² max		
Speed measurament range	min 0 0,1 m/s max 0 10 m/s		
Speed accuracy	< 2%		
Shock	100 G, 11 ms, single shock (IEC 60068-2-27)		
Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)		
Rod / housing material	1.4401 / AISI 316 stainless steel		
Operative pressure	350 bar (500 bar peak)		
Cursor type	floating cursor		
Temperature coefficient	≤ 0,01 % FS / °C		
Operating temperature	-30° +75°C (-22° +167°F)		
Storage temperature	-40° +100°C (-40° +212°F)		

CONNECTIONS				
Function	Cable output	C6 6 pin M16 connector		
+ V DC	brown	5		
OV	white	6		
<b>Output cursor 1</b> 0 10 V 4 20 mA	grey	1		
OV cursor 1	pink	2		
Inverse output cursor 1 10 0 V 20 4 mA	yellow	3		
OV inverse output cursor 1	pink	4		

C6 connector (6 pin) DIN 45322 solder side view FV





#### Cylinder mounting example



\* = 55 mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole

For correct installation of rod-type magnetostrictive transducers in hydraulic cylinders, remember that the cylinder head must be made of non-magnetic material where the threaded hole will be drilled to install the transducer. If not, the residual magnetisation caused by drilling the threaded hole must be less than 4 Gauss. Sealing surface must be free from scratches longitudinal or spiral

Ro 1,6 µm for sealing with non pulsating pressure Ro 0,8 µm for seals with pulsating pressure

Suggested o-ring (model H) Parker 6-349 15,4 x 2,1 Material: Viton 90° Shore A Mixes: Parker N552-90

Suggested o-ring (model I) Parker 3-908 16,36 x 2,21 Material: Viton 90° Shore A Mixes: Parker N552-90

#### Electrical connection example



The transducer must be installed away from sources of magnetic fields, both static and 50 Hz (electric motors, solenoids, etc.).

· with floating cursor assembly support must be made with nonmagnetic material

the transducer connection cable must be wired separate from power cables and/or solenoid controls, drives, or remote switches

 power supply must be drawn from dedicated power supply and connected directly to power terminals as near as possible
 since the transducer cursor is a magnet, make sure there are no iron filings or small fragments of magnetic metal near the transducer. This could produce an accumulation of material on the cursor, with consequent sliding problems • if the transducer is installed in a cylinder isolated from the ground, the cable shielding on PLC side must be grounded

· with multiple cursors (two or more), cursors distance must be minimum 75 mm each







# LINEAR MAGNETOSTRICTIVE ROD TRANSDUCER WITH SSI OUTPUT

#### MAIN CHARACTERISTICS

EMSSS is an absolute linear magnetostrictive transducer featuring a SSI output.

Main characteristics of magnetostrictive transducer is the absence of electric contact on the enclosure so there is no issue of wear and deterioration during working life guaranteeing high displacement speed and precision.

High reliability and simple installation even for applications with mechanical stresses, shocks or high contamination are assured by the compact size and the rugged enclosure.

This series has been designed for being mounted internally to high preassure (350 bar, 500 bar peak) such as hydraulic or pneumatic cylinders.







## EMSSA



dimensions in mm

• OR 15,4 x 2,1 (mod.H) / OR 16,36 x 2,21 (mod.I) included

· Cursors and female connector not included, for ordering P/N please refer to Accessories section

ELECTRICAL SPECIFICATIONS			
Resolution	5 - 10 - 20 - 40 μm		
Indipendent linearity	$\leq \pm 0.02\%$ FS (min $\pm 0.060$ mm)		
Repeatability	< 0,01 mm		
Hysteresis	≤ ± 0,005% FS (min 0,010 mm)		
Sampling time	1 ms (mod. 100 1000) 2 ms (mod. 1250 1500)		
Power supply	10 32 VDC		
Power ripple	1 Vpp max		
Max load current	50 mA max		
Output type	RS-422		
SSI output code	binary or gray		
Clock frequency	50 kHz 1 MHz		
SSI monostable time (Tm)	16 µs		
SSI frame	21 / 24 / 25 bit data length		
Counting direction	increase		
Protection against overvoltage	yes		
Protection against polarity inversion	yes		
Self-resetting internal fuse	yes		
Electrical insulation	500 VDC (+VDC / earth)		
Electromagnetic compatibility	according to 2014/30/EU directive		

MECHANICAL SPECIFICATIONS			
Stroke	100 - 150 - 200 - 300 - 400 - 450 - 500 - 600 - 700 - 800 - 900 - 1000 - 1250 - 1500 mm		
Electric stroke (EE)	see model (mm)		
Overall dimensions (LT)	EE + 176,2 mm (mod. 100 1000) EE + 181,2 mm (mod. 1250 1500)		
Enclosure rating	IP 67 (IEC 60529)		
Detected measurement	displacement		
Travel speed	10 m/s max		
Acceleration	100 m/s <sup>2</sup> max		
Speed measurament range	min 0 0,1 m/s max 0 10 m/s		
Speed accuracy	< 2%		
Shock	100 G, 11 ms, single shock (IEC 60068-2-27)		
Vibration	12 G, 10 2000 Hz (IEC 680068-2-6)		
Rod / housing material	1.4401 / AISI 316 stainless steel		
Operative pressure	350 bar (500 bar peak)		
Cursor type	floating cursor		
Temperature coefficient	20 ppm FS / °C		
Operating temperature	-30° +90°C (-22° +194°F)		
Storage temperature	-40° +100°C (-40° +212°F)		

CONNECTIONS				
Function	Cable output	C6 6 pin M16 connector		
+ V DC	blue / white	5		
0V	blue	6		
Data +	brown / white	2		
Data -	orange	1		
Clock +	green / white	3		
Clock -	green	4		

C6 connector (6 pin) DIN 45322 solder side view FV



#### Cylinder mounting example



\* = 55 mm up to stroke 1000 mm, from 1250 mm consider 60 mm due to M4 threaded hole

For the correct installation of rod-type magnetostrictive transducers in hydraulic cylinders, remember that the cylinder head must be made of non-magnetic material where the threaded hole will be drilled to install the transducer. If not, the residual magnetisation caused by drilling the threaded hole must be less than 4 Gauss. Sealing surface must be free from scratches longitudinal or spiral

Ro 1,6  $\mu m$  for sealing with non pulsating pressure Ro 0,8 µm for seals with pulsating pressure

Suggested o-ring (model H) Parker 6-349 15,4 x 2,1 Material: Viton 90° Shore A Mixes: Parker N552-90

Suggested o-ring (model I) Parker 3-908 16,36 x 2,21 Material: Viton 90° Shore A Mixes: Parker N552-90

#### **SSI BLOCK DIAGRAM**



SSI output goes to 0 if the echo is absent (magnet out of measurement range or internal device error)

SSI CABLE LENGTH					
Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m
Baud rate	1 Mbaud	400 kbaud	300 kbaud	200 kbaud	100 kbaud

#### Installation notes

The transducer must be installed away from sources of magnetic fields, both static and 50 Hz (electric motors, solenoids, etc.).

 $\cdot$  with floating cursor assembly support must be made with nonmagnetic material

· the transducer connection cable must be wired separate from power cables and/or solenoid controls, drives, or remote switches

power supply must be drawn from dedicated power supply and connected directly to power terminals as near as possible since the transducer cursor is a magnet, make sure there are no iron filings or small fragments of magnetic metal near the transducer. This could produce an accumulation of material on the cursor, with consequent sliding problems

cable shield must be connected on both sides (PLC and transducer)

if the transducer is installed in a cylinder isolated from the ground, the cable shielding on PLC side must be grounded.







# ACCESSORIES FOR LINEAR POTENTIOMETER / MAGNETOSTRICTIVE

#### **CURSORS FOR EMSPA - EMSPB - EMSPS**



Sliding cursor axial joint high EMS-CSA P/N 95490000 31 31 26







# **FLOATING CURSORS FOR EMSSA - EMSSS**

Floating cursor EMS-CAA



Floating cursor EMS-CAC



Floating cursor EMS-CAB



Floating cursor for liquids EMS-CAG12 / EMS-CAG15



Description	P/N	Material	Supplied with
EMS-CAA	95590000	aluminum	n.4 M4 brass nuts n.8 D4 brass washers n.4 M4x25 brass screws
EMS-CAB	95590001	aluminum	n.4 M4 brass nuts n.4 D4 brass washers n.2 M4x25 brass screws
EMS-CAC	95590011	aluminum	/
EMS-CAG12	95590012	AISI 316 stainless steel	12 mm hole
EMS-CAG15	95590013	AISI 316 stainless steel	15 mm hole

# COLLAR CLAMPING FOR EMS-CAG12 / EMS-CAG15



Description	P/N	Material	Supplied with
EMS-FG01	95590014	AISI 316 stainless steel	n.1 D3 AISI 316 washer n.1 M3x8 AISI 316 screw

dimensions in mm





#### **HEX NUT FOR EMSSA - EMSSS**



Description	P/N	Material	A
EMS-CD01	95590010	AISI 316 stainless steel	M18 x 1,5
EMS-CD02	95590015	AISI 316 stainless steel	3/4" - 16UNF

# **BRACKETS FOR EMSPA - EMSPB - EMSPS**





1

Description	P/N	Center-to-center (I)	Overall dimension (L)	Height (A)	Screw (M)
EMSPA-EMSPS-ST42	95490011	42,5	56	12,4	M4
EMSPA-EMSPS-ST50	95490010	50	63,5	12,4	M5
EMSPB-ST42	95490022	42,5	56	10	M4
EMSPB-ST50	95490026	50	63,5	10	M5

# EPLA BALL JOINT FOR EPLA

EPLA-SN01 Ball joint ø 6 P/N 95390003



dimensions in mm





Ø 18

Cable gland for cable ø 6 ... 8

Cable gland for

cable ø 6 ... 8

Ø 17

Ø 17



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26.

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