## **In-Place Inclinometer**



# Submersible

In-Place

### In-Place Inclinometer

#### Features

- According to ISO11898-2 standard, support CAN2.0B protocol
- Built-in high-speed optoelectronic isolation
- Set baud rate before delivery, support 5K-1000Kbps total 15 kinds of CiA recommended Baud rate
- Operation temperature -40  $^\circ\text{C}$  ~85  $^\circ\text{C}$
- Waterproof cable, 60 m submersible depth

#### Descriptions

In-Place inclinometer is based on Vigor patent tilt measurement technology and combined with CAN module, further its housing match with all civil engineering applications. It not only has high reliability & high performance, also easily connect each other with slave/master functions.

In-place inclinometer employee with MEMS technology, more durable, high stability to ensure getting higher accurate data and repeatability.

With high-speed optoelectronic isolation, CAN interface support ISO11898-2 standard and CAN2.0B standard protocol, baud rate can be set before delivery within 5~1000Kbps, adopt smaller frame structure (8bytes for each effective frame) with shorter transmission time, strong anti-interference ability. It supports point to point or one point to multipoint communication mode, suit for high speed data rate with longer communication distance.

CAN interface supports acknowledge model/continuous sending mode/parameter setting mode. User can setup CAN interface and set zero point/baud rate/local gravitational value/zero calibration/vibration suppression filter coefficients/ID address/refresh rate, etc..

#### Applications

Slot milling mixer, Civil engineering

#### Performances

#### Table 1 Specifications

Measurement range		±10°other range available		
Combined absolute		±0.015°		
accuracy <sup>⊕</sup> (@25℃)				
	Absolute linearity	+0.02		
	(LSF,%FS)	10.05		
Accuracy	Cross-axis			
subroutine	sensitivity®	±0.1%FS		
parameter	Offset <sup>®</sup>	±0.005°		
	Repeatability	±0.0025°		
	Hysteresis	±0.0025°		
Allowed in	stallation	±3.0°		
misaligr	nment@			
Input-axis n	nislignment	≤±0.1°		
Sensitivity tem	nperature drift	<100 mm //C		
coefficier	nt(max.)	S rooppin/ C		
Offset tempe	erature drift			
coefficier	nt(max.)	≤0.003 <sup>-7</sup> C		
Offset turn on	repeatability <sup>©</sup>	±0.008°		
Resol	ution	0.0025°		
Long-term stability <sup>®</sup> (1 year) <sup>®</sup>		≤0.02°		
Measurement axis		2 axis		
Temperatu	ire sensor	Range: -50~125℃, Accuracy:±1℃		
0		CAN2.0A,CAN2.0B , follow ISO11898-2 standard		
Out	put	5k~1 MBit/s, 15 kinds of CiA recommended Baud rate		
		Through CANbus to set and adjust zero point , Baud rate, local Gravitational		
Func	tion	acceleration value, zero correction, vibration suppression filter coefficients, ID		
		address, refresh rate		
Cold start wa	arming time	60s		
Respons	e time <sup></sup>	0.3s(@t <sub>90</sub> )		
Message send	ing frequency	1~20Hz		
Response f	requency <sup>®</sup>	3Hz @-3dB		
Power supply		9~36VDC		
Power consumption		Average working current≤200mA(25℃&24VDC)		
Operation temperature range		-40~85℃		
Storage temperature range		-60~100℃		
Insulation resistance		100ΜΩ		
MTBF		≥25000 h/times		
Shock		100g@11ms, three-axis, half-sine		
Vibration		8grms, 20~2000Hz		
Protection		 IP69К		
Connecting		Subconn MCIL5F		
	-			

① Combined absolute accuracy means the compositive value of sensor's absolute linearity, repeatability, hysteresis, offset and cross-axis sensitivity error. (in room temperature condition) as

 $\Delta = \pm \sqrt{absolute linearity^2 + repeatability^2 + hysteresis^2 + offset^2 + cross-axis sensitivity error^2}$ 

 $\Omega$  The cross-axis sensitivity means the angle that the tilt sensor may be banked to the normal tilt direction of sensor. The cross-axis sensitivity (±0.1%FS) shows how much perpendicular acceleration or inclination is coupled to the inclinometer output signal. For example, for the single-axis inclinometer with range ±30°(assuming the X-axis as measured tilt direction), when there is a 10° tilt angle perpendicular to the X-axis direction(the actual measuring angle is no change, example as +8.505°), the output signal will generate additional error for this 10° tilt angle, this error is called as cross-axis sensitivity error. SST300° s cross-axis sensitivity is 0.1%FS, the extra error is 0.1%×30°=0.03°(max), then real output angle should be +(8.505°±0.03°). In SST300 series, this error has been combined into the absolute accuracy

③ Offset means that when no angle input (such as the inclinometer is placed on an absolute level platform), output of sensor is not equal to zero, the actual output value is zero offset value.

④ Allowed installation misalignment means during the installation, the allow able installation angle deviation between actual tilt direction and sensor's nature measurement direction. In general, when installed, SST300 sensor is required that the measured tilt direction keep parallel or coincident with sensor designated edge, this parameter can be allowed a certain deviation when sensor is installed and does not affect the measurement accuracy.

(5) Offset turn on repeatability means the repeatability of the sensor in repeated by supply power on-off-on many times.

(6) Long-term stability means the deviation between the statistics of the maximum and the minimum output value after a year of continuous power supply when the sensor is at 20℃.

The response time refers to the angle sensor in a step change (such as the angle changes from -10 ° to +10 °within 5ms), the time required that output of the sensor achieved to the standard value of 90%. The index is different from the sensor set-up time

 Response frequency is for the limitation of the dynamic measurement range, when the dynamic measurement exceeds 3 Hz, because of centripetal force, the output occupied additional random error, this error is difficult to define.

#### Dimensions (mm)



#### Wiring



Table 2 Pin definition						
Pin	Color	Function				
1	Black	Power GND				
2	White	NC				
3	Red	Power+				
4	Brown	CANL				
5 Blue		CANH				

Picture 1 Connector socket (MCIL5F)

#### Ordering



For example: if order a In-Place sensor, with range  $\pm 10^{\circ}$ , room temperature accuracy  $\pm 0.015^{\circ}$ ,  $-20 \sim 60^{\circ}$ C accuracy  $\pm 0.02$ , CAN2.0B interface, 2 meters cable, the model should be chosen as: SST302-10-G3-00-B7-00-D3

#### Accessories

Table	3	Accessories
iubic	0	100003301103

Item	Order Code	Accessories name	Function
	G1	RS485 output	Standard industrial ModBus protocol
	G2	RS422 output	Standard industrial interface
Output	G3	CAN output	Standard industrial interface
interface	G9	Ethernet interface	Standard industrial TCP/IP interface
Interface	G19	4~20mA output	Standard industrial level
	G21	-5~+5VDC output	Standard industrial level
	G23	-10~+10VDC output	Standard industrial level
O a la la (Dhuar	C2	Tensile reinforced shield cable	Heavy duty up to 50kg
Cable/Plug	C4	Armor cover cable	Increasing mechanical strength, erosion and anti-interference ability.
	D1	Temperature drift	Temperature compensation range $0 \sim 60^{\circ}$ C, accuracy $\pm 0.01^{\circ}$ @ $\leq \pm 30^{\circ}$
	D2	Temperature drift	Temperature compensation range 0~60°C, accuracy ±0.01°@>±30°
	D3	Temperature drift	Temperature compensation range -20~60°C, accuracy $\pm 0.02^{\circ}@ \leq \pm 30^{\circ}$
Temperature	D4	Temperature drift	Temperature compensation range -20~60°C, accuracy ±0.02°@>±30°
drift	D5	Temperature drift	Temperature compensation range -30~60°C, accuracy $\pm 0.03^{\circ}@ \leq \pm 30^{\circ}$
	D6	Temperature drift	Temperature compensation range -30~60°C, accuracy ±0.03°@>±30°
	D7	Temperature drift	Temperature compensation range -40~65°C, accuracy $\pm 0.05^{\circ}@\leq \pm 30^{\circ}$
	D8	Temperature drift	Temperature compensation range -40~65°C, accuracy $\pm 0.05^{\circ}@>\pm 30^{\circ}$

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