## MAIN EXPORT COUNTRIES:



The company under the name **JSC "Precizika Metrology"** began work after the change of name of the Lithuanian - American Joint Venture "Brown & Sharpe - Precizika". The company has a proud history of old traditions in the leadership of design and production of metrological equipment. Its workforce has been involved for over fifty years in the supply of measuring technology and systems to automate factories as well as in the development of optical scale manufacturing technology.

In 2000, the production process was certified to fully meeting the requirements of EN ISO 9002:1994, in 2003 – EN ISO 9001:2000.

The company's goal is to consistently supply high quality products and services to meet customer demands on a timely basis. The company's main products are linear and angular glass scale gratings, and the linear and rotary displacement measuring systems.

JSC "Precizika Metrology" represents worldwide known companies and suppliers of measuring equipment, CNC centers, executes installation and services of them, trains the users, and executes upgrading of used CMM and manual cutting machine-tools.

## **458 HUGA** PHOTOELECTRIC ROTARY ENCODER

The encoder A58HM is used to measure angular position of the key machine components, industrial robots, comparators, rotary tables, servo drives and to establish an informational link with DCC, NC or Digital Readout Units. The encoder has integrated stator coupling so it can be fixed directly onto object shaft. Mounting adapter - similar to adapter of encoder A58H - is available on request. The encoder is used in automatic control, on-line gauging, process monitoring systems, etc. The housing of the encoder is fixed to an object by means of four screws M3 or through adapter. The fixation to object shaft is made by two screws M3. Three versions of output signals are available:

- A58HM-A sinusoidal signals, with amplitude approx. 11 µApp;
- A58HM-AV sinusoidal signals, with amplitude approx. 1 Vpp;
- A58HM-F square-wave signals (TTL or HTL) with integrated subdividing electronics • for interpolation x1, x2, x3, x4,x5, x8, x10.





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PRECIZIKA METROLOGY





# A58HM

## **RECOMMENDED APPLICATIONS**



**MECHANICAL DATA** 

Line number on disc (z)

Maximum shaft speed

Permissible motion of shaft:

- radial (at shaft end)

Accuracy (T,-period of lines on disc

- on option for z < 5000

- on option for z > 5000

for A58-F

- axial

in arc. sec)

Pulse number per shaft revolution



MILLING / BORING /

DRILLING CNC MAC



100; 250; 500; 600; 800;

5000; 9000; 10800

10000 rpm

±0.03 mm

±0.1T, arc. sec

±0.05<sup>1</sup>, arc. sec

±12.0 arc. sec

0.05 mm

(k - interpolation factor)

1000; 1024; 1125; 1250; 1500;

2000; 2500; 3000; 3600; 4000;

Z x k, where k=1,2,3,4,5,8,10

















< 0.025 Nm

IP64

IP64

0.35 kg

0...+70 °C

 $\leq$  300 m/s<sup>2</sup>

-30...+80 °C

< 1.5x10<sup>-4</sup> kgm<sup>2</sup>

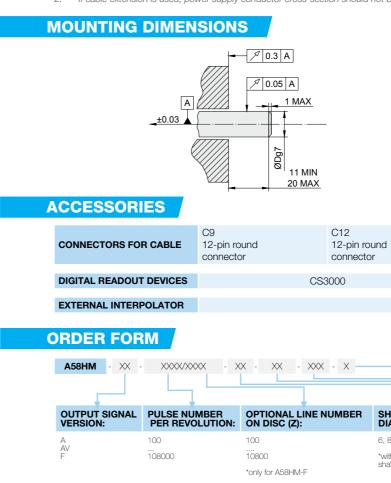
ELECTRICAL DATA

VERSION	А58НЕ-А 🔨 11 µАрр	A58HE-AV 🔨 1 Vpp	A58HE-F TLI TTL; TLI HTL
Supply voltage (U <sub>P</sub> )	$+5 V \pm 5\%$	$+5 V \pm 5\%$	+5 V $\pm$ 5%; +(10 to 30) V
Max. supply current (without load)	80 mA	120 mA	120 mA
Light source	LED	LED	LED
Incremental signals	Two sinusoidal I, and I, Amplitude at 1 kΩ load: - I1 = 7-16 μA - I2 = 7-16 μA	Differential sine +A/-A and +B/-B Amplitude at 120 Ω load: - A = 0.6-1.2 V - B = 0.6-1.2 V	Differential square-wave U1/U1 and U2/U2. Signal levels at 20 mA load current: - low (logic "0") $\leq 0.5$ V at U <sub>p</sub> =+5 V - low (logic "0") $\leq 1.5$ V at U <sub>p</sub> =10 to 30 V - high (logic "1") $\geq 2.4$ V at U <sub>p</sub> =+5 V - high (logic "1") $\geq (U_p$ -2) V at U <sub>p</sub> =10 to 30 V
Reference signal	One quasi-triangular I_b peak per revolution. Signal magnitude at 1 k $\Omega$ load: -I_b = 2-8 $\mu A$ (usable component)	One quasi-triangular +R and its com- plementary -R per revolution. Signals magnitude at 120Ω load - R = 0.2-0.8 V (usable component)	One differential square-wave U0/U0 per revolution. Signal levels at 20 mA load current: - low (logic "0") < 0.5 V at $U_p=+5$ V - low (logic "0") < 1.5 V at $U_p=10$ to 30 V - high (logic "1") > 2.4 V at $U_p=+5$ V - high (logic "1") > ( $U_p$ -2) V at $U_p=10$ to 30 V
Maximum operating frequency	(-3 dB) ≥ 160 kHz	(-3 dB) ≥ 180 kHz	(160 x k) kHz, k-interpolation factor
Direction of signals	I2 lags I1 for clockwise rotation	B lags A for clockwise rotation	U2 lags U1 with clockwise rotation
Maximum rise and fall time		-	< 0.5 µs
Standard cable length	1 m, without connector	1 m, without connector	1 m, without connector
Maximum cable length	5 m	25 m	25 m
Output signals	I <sub>1</sub> I <sub>2</sub> I <sub>0</sub> 90° et. 360° et.	+A +B +R 90° el. 360° el.	

Note:

1. Maximum working rotation speed (with proper encoder counting) is limited by maximum operating frequency and maximum mechanical rotation speed.

2. If cable extension is used, power supply conductor cross-section should not be smaller than 0.5 mm<sup>2</sup>.

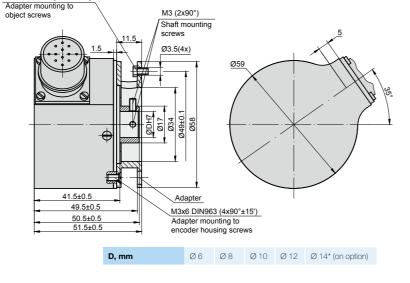


ORDER EXAMPLES:

## 1) A58HM-AV-1024-6-05V-C12-W 2) A58HM-F-4000-8-30V-C12-S 3) A58HM-F-4000/500-8-30V-C12-S

M3x5 DIN933 (4x90°±15') /Adapter mounting to object screws M3x5 DIN933 (4x90°±15') Ø49±0.1 22.5 (C12)

Encoder without adapter Ø48±0.1 ø M3-6Hx5 (4x90°±15')



MACHINES

Starting torque at 20°C

Rotor moment of inertia

Operating temperature

Storage temperature

Permissible shock (11 ms)

Protection (housing) (IEC 529)

Protection (shaft side) ( IEC 529)

Maximum weight without cable

Maximum humidity (non-condensing) 98 %

Permissible vibration (55 to 2000 Hz)  $\leq$  100 m/s<sup>2</sup>



VER Supp Max.



### ADAPTER

