Ranged Inclinometer





Ranged Inclinometer

Features

- Measuring three-dimensional angle information: roll, pitch and heading
- Maximum measuring range for roll/pitch angle: $\pm 60^\circ$
- Heading accuracy ±5°RMS@≤±30°, resolution 0.01°
- Tilt repeatability accuracy±0.0025°
- Refresh rate 5~20Hz
- Customized higher accuracy and dynamic nature products
- Patented tilt measurement technology to realize real high accuracy

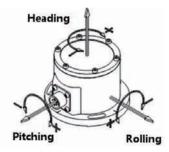
Descriptions



Ranged inclinometer is developed to detect target motion objects' three-dimensional attitude, meanwhile output heading angle(relative to the arctic) and X/Y axis angle data(relative to the absolute horizontal plane). Mainly applicable to high precision tilt angle measurement and need heading data in indoor or outdoor industrial field.

Ranged inclinometer is a complement for GPS inclinometer, can realize X, Y, Z three direction attitude measuring without space restrictions, with stable and reliable heading data, calibration function for soft iron and hard iron, eliminate ambient magnetic which influence heading measurement accuracy. It suits for vehicle, onboard, ship and robot application.

- $\sqrt{\pm 0.02\%}$ FS linearity
- $\sqrt{\pm 0.005^{\circ} \text{Offset}}$
- ✓ Combine with gyro module, realize static/dynamic angle different measuring for low/rapid leveling
- ✓ Combine with vibration module, realize FFT computations different in-time, output vibration frequency and amplitude different data directly, eliminate the influence of environment different vibration



- ✓ Combine with GPS module, realize data synchronization data acquisition and local position data in different installation places
- \checkmark Further confirmed that offset, repeatability, hysteresis, turn on repeatability etc. parameters which are important influence factors to unit total performance evaluation
- ✓ Internal enhanced advanced intelligent algorithms drastically reduce cross-axis sensitivity, upgrades real tilt angle measuring accuracy, abandoned the traditional incomplete understanding for tilt angle measurement precision concept
- \checkmark Greatly reduce measuring errors when the real tilt direction not consistent for unit's actual sensitive axis
- \checkmark Short-circuit, transient voltage and transposition protection to adapt to industry environment
- $\checkmark~$ User can set unit parameters and query factory data

Applications

Navigation, Communication radar, Microwave directional, Offshore platform control, Antenna engineering, Unmanned aircraft or vehicle, Robot, Motion orientation, Automatic control

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Performances

Table	1	Specifications
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	Roll/ pitch performances						
Moasuro	ment range	±5°	±10°	±15°	s ±30°	±45°	±60°
	U U	ΞJ	±10	±15	±30	±40	±00
Combined absolute accuracy [©] (@25°C)		±0.01°	±0.015°	±0.02°	±0.04°	±0.06°	±0.08°
	Absolute linearity (LSF,%FS)	≤0.06	≤0.03	≤0.03	≤0.03	≤0.02	≤0.02
Accuracy subroutine	Cross-axis sensitivity@	≤0.1%FS					
parameter	Offset 3	≤0.005° ≤0.008°					
	Repeatability	≤0.0025°					
	Hysteresis	≤0.0025°					
	installation gnment [@]	$\pm 4.0^{\circ}$	±3.0°	±2.5°	±1.5°	±1.2°	±1.2°
	-			≤±C).1°		
Input-axis mislignment Sensitivity temperature drift Coefficient (max.)		≤100ppm/℃ ≤50ppm/℃					
Offset temperature drift coefficient (max.)		≤0.003°/°C					
Offset turn on repeatability [®]		≤0.008°					
Resolution		0.0025°					
Long-term stability(1 year) [®]		<0.02°					
Measure	ement axis	2 axis					
		Hea	ding perforn	nances			
Acc	uracy℗	<	±5° RMS @	tilt range < ±	±30°, ±0.5	° RMS @leve	l
Repeatability		±0.3°					
Resolution		0.01°					
			Tot				
	ture sensor	Range: -50~125℃, Accuracy: ±1℃					
0	utput	RS232,RS422,RS485					
Fui	nction	Set zero point, baud rate, local gravitational acceleration value, zero calibrativity vibration suppression filter coefficients, ID address, refresh rate, etc					
Cold start	warming time			60)s		
Refre	esh rate	5Hz, 10Hz, 20Hz					
Powe	r supply	9 ~ 36VDC					
Power co	onsumption	Average working current≤60mA, average power≤1.5W (25℃ &24VDC)					
Operation temp	erature range	-20~70°C					
5	perature range	- 40~85℃					
E	EMC	According to EN 61000					
	n resistance	100ΜΩ					
	ITBF	≥25000 h/times					
	hock	100g@11ms,three-axis, half- sine					
Vib	oration	8grms,20 ~ 2000Hz					
	tection	IP65(Optional IP67)					
	necting	cting Military class connector (MIL-C-26482)					
W	eight		500g(without con	nector and c	able)	

Combined absolute accuracy means the compositive value of sensor's absolute linearity, repeatability, hysteresis, offset and cross-axis sensitivity error.
(in room temperature condition) as

 $\Delta = \pm \sqrt{absolute linearity^2 + repeatability^2 + hysteresis^2 + offset^2 + cross-axis sensitivity error^2}$

The cross-axis sensitivity means the angle that the tilt sensor may be banked to the normal tilt direction of sensor. The cross-axis sensitivity (\pm 0.1%FS) shows how much perpendicular acceleration or inclination is coupled to the inclinometer output signal. For example, for the single-axis inclinometer with range \pm 30° (assuming the X-axis as measured tilt direction), when there is a 10° tilt angle perpendicular to the X-axis direction(the actual measuring angle is no change, example as +8.505°), the output signal will generate additional error for this 10° tilt angle, this error is called as cross-axis sensitivity error. SST300° s cross-axis sensitivity is 0.1%FS, the extra error is 0.1%×30°=0.03°(max), then real output angle should be +(8.505°±0.03°). In SST300 series, this error has been combined into the absolute accuracy

③ Offset means that when no angle input (such as the inclinometer is placed on an absolute level platform), output of sensor is not equal to zero, the actual output value is zero offset value.

④ Allowed installation misalignment means during the installation, the allow able installation angle deviation between actual tilt direction and sensor's nature measurement direction. In general, when installed, SST300 sensor is required that the measured tilt direction keep parallel or coincident with sensor designated edge, this parameter can be allowed a certain deviation when sensor is installed and does not affect the measurement accuracy.

(5) Offset turn on repeatability means the repeatability of the sensor in repeated by supply power on-off-on many times.

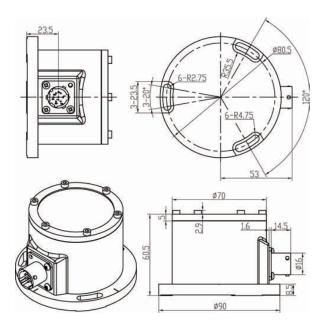
(6) Long-term stability means the deviation between the statistics of the maximum and the minimum output value after a year of continuous power supply when the sensor is at 20°C.

⑦ In actual use process, calibrate electronic compass in the main system, can get more accurate.

GPS

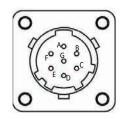
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Dimensions (mm)



Picture 1 Housing with MIL class connector

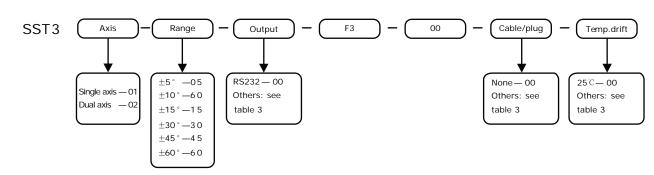
Wiring



Picture 2 MIL connector socket (View from outside)

Ordering

Table 2 MIL connector socket pin definition				
Pin	RS232	RS485	RS422	
А	Power+	Power+	Power+	
В	Power GND	Power GND	Power GND	
С	Signal GND	Signal GND	Signal GND	
D	NC	NC	RXD+	
E	NC	NC	RXD-	
F	TXD	RS485-A	TXD+	
G	RXD	RS485-B	TXD-	



For example, if order a Ranged inclinometer, with range $\pm 15^{\circ}$, room temperature accuracy $\pm 0.02^{\circ}$, $-20 \sim 60^{\circ}$ C accuracy $\pm 0.02^{\circ}$, two meters cable with plug, the model should be chosen as: SST302-15-00-F3 -00-C11-D3(2m) .

Meanwhile some options (See table 4):

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Accessories & Options

Table 3 Accessories					
Item	Order Code	Accessories name	Function		
Output interface	00	RS232	Directly angle output Data format: Baud rate: 115200(adjustable), 8 data bits, 1 start bit, 1 stop bit, none parity Refresh rate: 5Hz, optional: 10Hz, 20Hz		
	G1	RS485	Isolated, Compatible with half-duplex or full-duplex communication; ±15kV ESD protection Compatible with ANSI/TIA/EIA-485-A-98 & ISO8482:1987(E)		
	G2	RS422	Comply with UL15772500V rms for 1min ; Transmission rate up to 500 kbps, support max 256pcs node High common mode transient suppression ability>25kV/us ; Support Modbus-RTU, sensor supply HEX or ASCII communication		
Cable/Plug	C1	Standard plug with Cable	Meet MIL-C-26482,Standard 2m cable,IP67 protection, heavy duty up to 30kg		
	C6	Standard plug	Meet to MIL-C-26482		
	D1	Temperature drift	Temperature compensation range $0 \sim 60^{\circ}$ C, accuracy $\pm 0.01^{\circ}$ @ $\leq \pm 30^{\circ}$		
	D2	Temperature drift	Temperature compensation range $0 \sim 60^{\circ}$ C, accuracy $\pm 0.01^{\circ}@>\pm 30^{\circ}$		
	D3	Temperature drift	Temperature compensation range -20~60°C, accuracy ±0.02°@≤±30°		
	D4	Temperature drift	Temperature compensation range -20~60°C, accuracy ±0.02°@>±30°		
Temperature	D5	Temperature drift	Temperature compensation range -30~60°C, accuracy ±0.03°@≤±30°		
drift	D6	Temperature drift	Temperature compensation range -30~60°C, accuracy $\pm 0.03^{\circ}@>\pm 30^{\circ}$		
	D7	Temperature drift	Temperature compensation range -40~65℃, accuracy ±0.05°@≤±30°		
	D8	Temperature drift	Temperature compensation range -40~65°C, accuracy $\pm 0.05^{\circ}@>\pm 30^{\circ}$		
	D9	Temperature drift	Temperature compensation range -40~85°C, accuracy $\pm 0.05^{\circ}@\leq \pm 30^{\circ}$		
	D10	Temperature drift	Temperature compensation range -40~85°C, accuracy $\pm 0.05^{\circ}@>\pm 30^{\circ}$		

Table 4 Options

Item	P/N	Option name	Function		
Installation	SST003-01-04	Adjustable base with	Three-points adjustment, resolution 0.001mm,		
tools	551003-01-04	micrometer screw	stainless steel materials		
Power SST003-09-02	Dortable better / peeks	Output 24VDC,Continuous work 24			
	Portable battery packs	hours, IP65, rechargeable			
	SST003-11-01	Test report for cross-axis	Test report under banking tilt, average 11 points of full		
Teet	331003-11-01	sensitivity	range		
Test SST003-11-02		Absolute linearity	Average 21 points of full range		
report	SST003-11-03	Test report for Allowed	Axis migration test report for vertical and horizontal		
		Installation misalignment	axis of inclinometer, 3 angles of point		

GPS

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