

Quality - made in Germany



## RSM 59 - SSI

### Absolute multi-turn encoder

- shockproof up to 200 g
- electrical adjustment
- high code change frequency
- 36 bit resolution

#### Technical data

Resolution	36 Bit
Steps/Turn	262.144
Turns	262.144
Code	Gray, Binary
Interface	SSI

#### Electrical data

Operating voltage	UB = 10...30 VDC
Current consumption	Max. 80 mA (w/o load), at 24 VDC
Code change frequency	26 MHz
SSI Pulse frequency	62,5 kHz to 1,5 MHz
Monoflop time	20µs
Pulse break	Min. 25 µs
Accuracy	± 0,01°

#### Inputs

Level High	> 0,7 UB
Level Low	< 0,3 UB

#### Connections:

zeroing input with  
 10 kohms against GND.  
 The change of rotation  
 is only in the factory  
 possible.  
 Delivery status CW

#### Outputs

SSI Data	RS 422
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#### Mechanical data

Speed (mechanical)	≤ 10.000 min <sup>-1</sup>
Speed (electrical)	≤ 6.000 min <sup>-1</sup>
Start-up torque	< 0,015 Nm
Shaft loading	< 40 N radial < 20 N axial
Moment of inertia	18,4 x 10 <sup>-7</sup> kgm <sup>2</sup>

#### Material

Housing	Aluminium
Flange	Aluminium
Weight	approx. 600 g

#### Ambient conditions

Vibration	DIN EN 60068-2-6 ≤ 100 ms <sup>-2</sup> , 10...2000 Hz
Shock	DIN EN 60068-2-27 ≤ 500 m/s <sup>2</sup> ; 11 ms
Operating temperature	- 20... + 85° C
Storage temperature	- 20... + 85° C
Humidity	Max. relative humidity 95 % no-condensing

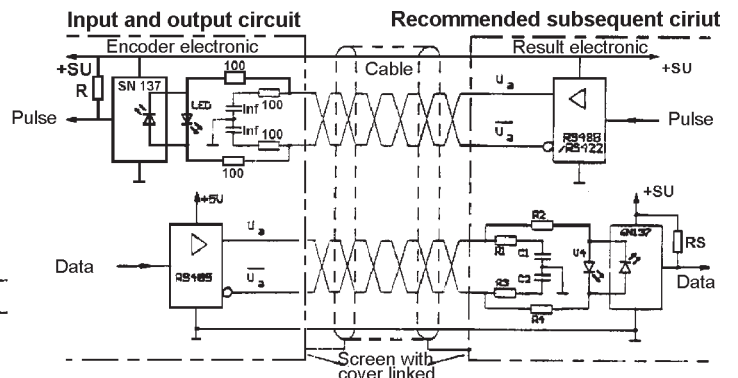
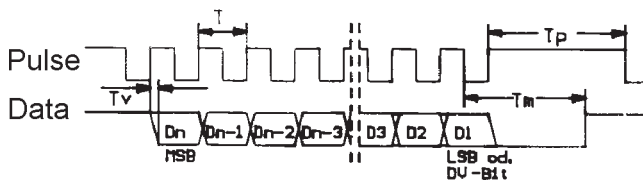
Protection type	IP 64
Interference resistance	DIN EN 61000-6-2
Emitted interference	DIN EN 61000-6-4

## Contact description

- 1 UB Encoder power supply connection
- 2 GND Encoder ground connection. The voltage drawn to GND is UB.
- 3 Pulse + Positive SSI pulse input. Pulse - forms a current loop with pulse +. A current of approx. 7 mA in direction of Pulse + input generates a logical 1 in positive logic.
- 4 Data + Positive, serial data output of the differential line driver. A High level at the output corresponds to logical 1 in positive logic.
- 5 Zero adjustment Zero setting input for setting a zero point at any desired point within the entire resolution. The zeroing process is triggered by a High pulse (pulse duration  $\geq 100$  ms) For maximum interference immunity, the input must be

- connected to GND after zeroing.
- 6 Data - Negative, serial data output of the differential line driver. A High level at the output corresponds to logical 0 in positive logic.
- 7 Pulse - Negative SSI pulse input. Pulse - forms a current loop with pulse +. A current of approx. 7mA in direction of Pulse - input generates a logical 0 in positive logic.
- 8 not in use
- 9 not in use
- 10 not in use
- 11 not in use
- 12 not in use

## SSI (Synchron serielles Interface)



# PIN - assignment RSM 59 - SSI

Signal	PIN	Cable colour
UB	1	brown
GND	2	white
Pulse +	3	green
Data +	4	pink
Adjustment	5	black
Data -	6	gray
Pulse -	7	yellow
not in use	8	-
not in use	9	-
not in use	10	-
not in use	11	-
not in use	12	-

**Instructions:**  
 Zero adjustment for setting a zero point at any desired point within the entire resolution. The zeroing process is triggered by a High pulse (pulse duration  $\geq 100$  ms) For maximum interference immunity, the input must be connected to GND after zeroing.

Please refer to the rating plate for the correct **power supply**.

Please don't occupied not used signals.

## Type key of encoder

Encoder type	Bit/Turn	Turns	Code	Voltage	Flange	Output
RSM 59	18 = 262.144 S/T	18 = 262.144 S/T	G = Gray	3 = 10 - 30 VDC	W 1 = 10 mm shaft clamping flange	KS = Cable radial
RSM 59			B = Binary			SS = 12pol. plug radial
RSM 59						
RSM 59						
RSM 59	18	18	_____	3	W1	_____

# Dimension and cutout RSM 59 - SSI

