### WS7.0 Position Sensor with Absolute or Incremental Encoder





### **Compact Industrial Sensor for Long Ranges**

Measurement Range:

0 ... 3750 mm to 0 ... 40000 mm

0 ... 147.6 in to 0 ... 1574.8 in

• With Absolute or Incremental Encoder Output

**Specifications** 

Oltputs	Incremental Encoder		
	Absolute Multiturn Encoder with synchronous serial output TSSI / RS-485		
Resolution	Incremental: 1, 5 or 10 pulses per mm; 25.4, 127 or 254 pulses per in TSSI: 0.073 mm up to 30000 mm range 0.088 mm up to 40000 mm range TSSI-P: 0.037 mm up to 30000 mm range 0.044 mm up to 40000 mm range		
Material	Aluminium and Stainless Steel Cable: Stainless Steel		
Sensing device	Incremental or Absolute Encoder		
Linearity	Up to ±0.05 % F.S., optional ±0.01 % F.S.		
Weight	Up to 4 kg max.		
Environmental			
Immunity to Interference (EMC)	Refer to Output Specification		
Temperature	Refer to Output Specification		

WS7.0 -

### Order code WS7.0 Absolute/Incremental Model Name



3750 / 5000 / 7500 / 10000 / 15000 / 20000 / 25000 / 30000 / 40000

#### Pulses per mm for Incremental Output PP530

= 10 Pulses per mm; 254 pulses per in

= 5 Pulses per mm, 127 pulses per in

= 1 Pulse per mm; 25.4 pulses per in (not in the 40000 mm range)

### Outputs

= Mechanism only for installation of suitable multiturn encoders

PP530 = Incremental output

= Multiturn encoder with synchronous serial output TSSI-P = TSSI prgrammable, RS232C, incremental signals Other Outputs on Request (Interbus S, Profibus, CAN-Bus)

L01 =  $\pm 0.01$  %, related to the specified sensitivity on the label (PP530)

#### **Option**

= M4 cable fixing M4

Order Code Mating Conn. (see accessories p. 105) | WS-CONN-D8 | TSSI(-P): | WS-CONN-017S-M

Order Example: WS7.0 - 30000 - 5 - PP530 - M4

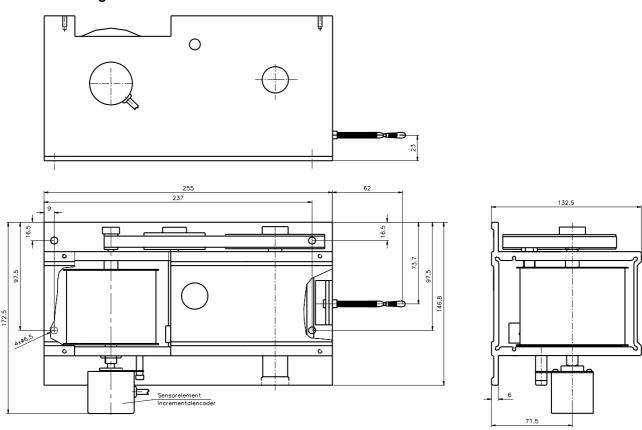
58 CAT-POS-E-2001 ASM

## **WS7.0 Position Sensor**with Absolute or Incremental Encoder



Cable Forces	Range [mm] [in]	Maximum Pull-out Force [N]	Minimum Pull-in Force [N]
typical at 20 °C	3750 - 147.6 - 30000 1181.1	8.0	4.2
	40000 1574.8	7.0	3.4

### **Outline drawing**



For guaranteed dimensions consult factory

ASM CAT-POS-E-2001 59

# WS Position Sensors Output Specification PP530



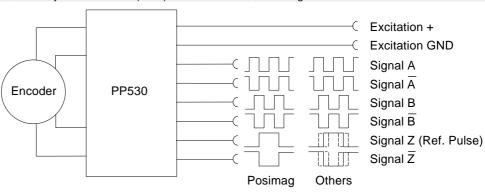
### Signal Conditioner PP530

Incremental

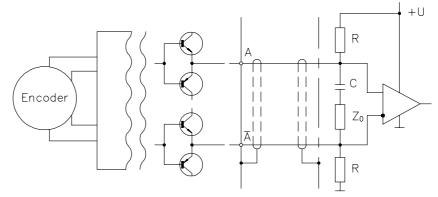


Excitation Voltage	+5 +30 VDC
Excitation Current	200 mA max.
Output Frequency	200 kHz max.
Output	Linedriver, Push-Pull, CMOS, TTL and HTL compatible
Output Current	30 mA max., Short Circuit Protection
Output Voltage	Depends on the excitation voltage (e.g. to obtain TTL-signals the excitation must be 5 V) Compatible to EIA RS-422/RS-485
Stability (Temperature)	±0.002% / K Full Scale (sensor mechanism)
Operation Temperature	-10 +70 °C
Storage Temperature	-30 +80 °C
Transition Time Positive Edge	250 ns
Transition Time Negative Edge	250 ns
Protection	Reverse Polarity, Permanent Short Circuit
Immunity to Interference (EMC)	According to EN61326: 1998

### Signal Diagram



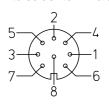
Recommended Processing Circuit



0'	Excitation	Level	la ≤ 5 mA	la≤ 25 mA	-la≤5 mA	-la ≤ 25 mA
Signal Levels	5 V	Ua <sub>High</sub>	>4.2 V	>4.2 V	>4.1 V	>3.8 V
	5 V	Ua <sub>Low</sub>	<0.5 V	<1.2 V	<0.4 V	<0.4 V
	24 V	Ua <sub>High</sub>	>23.5 V	>23.5 V	>23.5 V	>22.5 V
	24 V	Ualow	<0.5 V	<1.2 V	<0.4 V	<0.4 V

Signal Wiring / Connection	Output Signals PP530	Connector WS-CONN-D8
	Excitation +	1
	Excitation GND (0V)	2
	Signal B (A + 90°)	3
	Signal A	4
	Signal B	5
	Signal A	6
	Signal Z (Ref. Pulse)	7
	Signal Z	8

Mating connector View to solder terminals



WS-CONN-D8

ASM CAT-POS-E-2001 85

## WS Position Sensors Output Specification TSSI

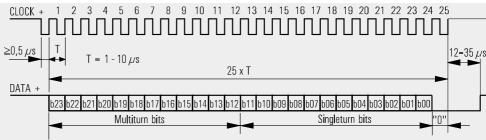


- 4096 counts per revolution (12 bit), 4096 revolutions (12 bit)
- No Loss of Data at Power-down
- Easy to Connect to PLC's with SSI Input Circuit

#### Description

The sensing device of the SSI is a 24-bit absolute multiturn encoder. The position information is given by an analog/digital converter output serialized as a data word. The processing unit (PLC, Microcomputer) sends pulse sequences which clocks the data transmission at the required transfer rate. With the first falling edge of the pulse sequence the position of the sensor is recorded and stored. The following rising edges control the bit-by-bit transmission of the data word. After a delay time the next new position information

### Data Format (Train of 26 pulses)



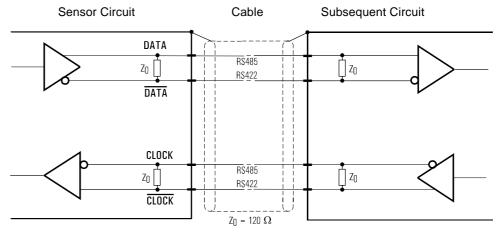
### Signal Conditioner TSSI

Absolute Encoder synchronous serial



Output	EIA RS-422, RS-485, short-circuit proof
Excitation Voltage	10 30 V DC, reverse polarity protected
Excitation Current	250 mA max. without load
Clock Frequency	100 kHz 1 MHz
Code	Gray, continuous progression
Format	Tannenbaum
Delay between Pulse Trains	12 to 35 µs
Stability (Temperature)	±0.002% / K Full Scale (sensor mechanism)
Operation Temperature	-20 +85 °C
Immunity to Interference (EMC)	According to EN50082-2, EN50081-1

### Recommended Processing Input Circuit



Cable Length Baud Rate
50 m 100 ... 1000 kHz

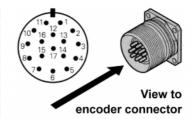
Note:

Extension of the cable length will reduce the maximum transmission rate.

The signals CLOCK/CLOCK and DATA/DATA must be connected in a twisted pair cable, shielded per pair and common.

Signal Wiring /	Signal Name	Cable Output (*)	Connector Pin
	Excitation +	white	7
Connection	Excitation GND (0V)	brown	10
	CLOCK	green	8
	CLOCK	yellow	9
(*) WS7.2 only	DATA	grey	14
	DATA	pink	17

100 m



ASM CAT-POS-E-2001 89

100 ... 300 kHz

## WS Position Sensors Output Specification TSSI-P

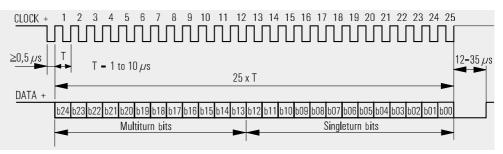


- 8192 counts per revolution (13 bit), 4096 revolutions (12 bit)
- Encoder programming and data transfer via RS-232 interface
- . In addition sinusoidal incremental signals

#### Description

The sensing device of the SSI is a 25-bit absolute multiturn encoder. The position information is given by an analog/digital converter as a serial data word. The processing unit (PLC, Microcomputer) sends pulse sequences which clocks the data transmission at the required transfer rate. With the first falling edge of the pulse sequence the position of the sensor is recorded and stored. The following rising edges control the bit-by-bit transmission of the data word. After a delay time the next new position information will be transmitted.

## **Data Format** (Train of 26 pulses)



### Signal Conditioner TSSI

Absolute Encoder synchronous serial, programmable



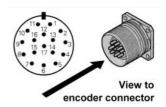




Output	EIA RS-422, RS-485, short-circuit proof
Excitation Voltage	10 30 V DC, reverse polarity protected
Excitation Current	250 mA max. without load
Clock Frequency	100 kHz 1 MHz
Programmable Functions	Resolution, Offset, Preset, Counting Direction, Output Code and Format
Code	Gray or Binary
Format	Tannenbaum (SSI) or Serial, right aligned
Delay between Pulse Trains	12 to 35 μs
Incremental Signal	Two sinusoidal quadrature signals A and B, each with 512 periods per revolution. Signal amplitude approx. 1 $V_{SS}$ with 120 $\Omega$ terminating resistance
Serial Interface	RS-232C asynchronous (TxD, RxD, GND) for encoder programming and data transmission
Hardware Programming	Preset1, Preset2, Counting Direction
Stability (Temperature)	002% / K Full Scale (sensor mechanism)
Operation Temperature	-20 +85 °C
Immunity to Interference (EMC)	According to EN50082-2, EN50081-1

### Signal Wiring / Connection

Signal Name	Connector Pin
Excitation +	7
Excitation GND (0V)	10
CLOCK	8
CLOCK	9
DATA	14
DATA	17
Signal A	15
Signal A	16
Signal B	12
Signal B	13
Internal shield	11
RxD	1
TxD	4
Fault detection signal UaS	3
Preset1	5
Preset2	6
Counting direction	2



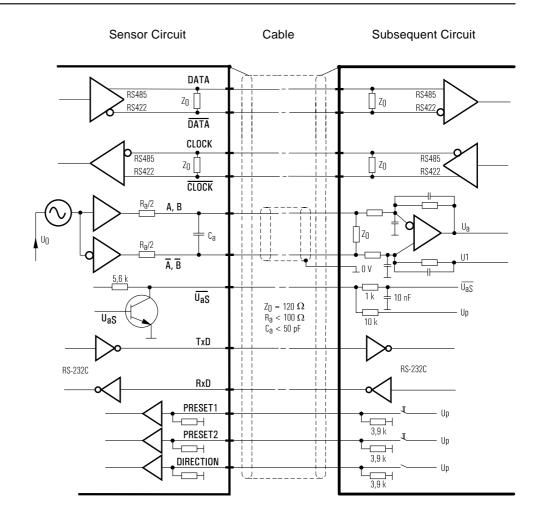
Programming Software and Connector Cable see page 104.

90 CAT-POS-E-2001 ASM

## WS Position Sensors Output Specification TSSI-P



Recommended Processing Input Circuit



Cable Length Baud Rate

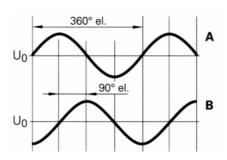
50 m 100 ... 1000 kHz 100 m 100 ... 300 kHz Note:

Extension of the cable length will reduce the maximum transmission rate.

The signals CLOCK/CLOCK and DATA/DATA

must be connected in a twisted pair cable, shielded per pair and common.

Incremental Signals



ASM CAT-POS-E-2001 91